EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	105	Neural and network and plant and "control system" and cost and function and phase and amplitude and @ad<"20030828"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF ·	2007/04/26 13:19
L3	1019	(706/15 or 706/19 or 706/906 or 700/7) and @ad<"20030828"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/04/26 13:43
L4	904	neural and network and control and plant and model and cost and function and @ad<"20030828"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/04/26 13:44
L5	170	4 and amplitude and phase and system	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/04/26 13:44

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	·		3.	An optimal tracking neuro-c Young-Moon Park; Myeon-Sc Neural Networks, JEEE Trans Volume 7, Issue 5, Sept. 199 Digital Object Identifier 10.110 AbstractPlus References F Rights and Permissions	ong Choi; Lee, K.Y.; <u>actions on</u> 96 Page(s):1099 - 1110 09/72.536307						
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			5.	Nonlinear predictive contro Song, B.J.; Koivo, A.J.; Industrial Electronics. IEEE T Volume 46, Issue 5, Oct. 19 Digital Object Identifier 10.110	ransactions on 99 Page(s):923 - 932	anipulator with flexible forear	m				
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